



# basic education

Department:  
Basic Education  
**REPUBLIC OF SOUTH AFRICA**

## **NATIONAL SENIOR CERTIFICATE**

**GRADE 12**

**ELECTRICAL TECHNOLOGY**

**FEBRUARY/MARCH 2015**

**MARKS: 200**

**TIME: 3 hours**

**This question paper consists of 13 pages and a 2-page formula sheet.**



**INSTRUCTIONS AND INFORMATION**

1. This question paper consists of SEVEN questions.
2. Answer ALL the questions.
3. Sketches and diagrams must be large, neat and fully labelled.
4. Show ALL calculations and round off correctly to TWO decimal places.
5. Number the answers correctly according to the numbering system used in this question paper.
6. You may use a non-programmable calculator.
7. Show the units for all answers of calculations.
8. A formula sheet is provided at the end of this question paper.
9. Write neatly and legibly.



**QUESTION 1: OCCUPATIONAL HEALTH AND SAFETY**

- 1.1 State TWO unsafe acts that may lead to an electric shock in a workshop. (2)
- 1.2 State THREE safety procedures that should be followed when a person is being electrocuted. (3)
- 1.3 Human rights and work ethics are principles that are important to all South Africans. Discuss how you would promote these principles with reference to gender. (2)
- 1.4 State THREE considerations when conducting a risk analysis to prevent accidents in an electrical technology workshop. (3)
- [10]**

**QUESTION 2: THREE-PHASE AC GENERATION**

- 2.1 State TWO advantages of three-phase power generation over single-phase power generation. (2)
- 2.2 Make a sketch of the voltage waveforms generated by a three-phase generator. (3)
- 2.3 The output power of a three-phase AC generator that generates 380 V is measured using the two wattmeter method. The readings on the wattmeters are 700 W and -290 W respectively. Calculate the output power of the generator.
- Given:
- $W_1 = 700 \text{ W}$   
 $W_2 = -290 \text{ W}$   
 $V_L = 380 \text{ V}$  (3)
- 2.4 A delta-connected generator delivers power to a balanced star-connected inductive load. The phase current of the generator is 18 A and the line voltage is 380 V. The current lags the voltage by  $14^\circ$ .

Given:

$$V_L = 380 \text{ V}$$
$$I_{PH} = 18 \text{ A}$$
$$\Theta = 14^\circ$$

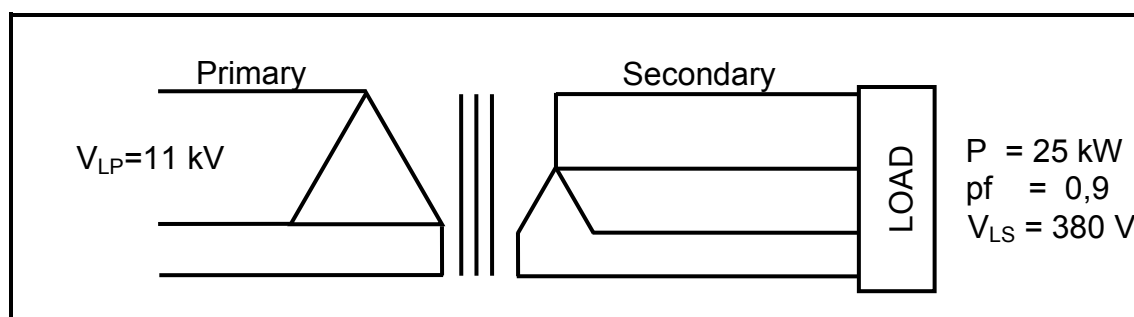
Calculate the:

- 2.4.1 Line current of the generator (3)
- 2.4.2 Phase voltage of the load (3)
- 2.4.3 Impedance of each phase (3)
- 2.4.4 True power delivered by the generator (3)
- [20]**



**QUESTION 3: THREE-PHASE TRANSFORMERS**

- 3.1 Name TWO types of transformer constructions. (2)
- 3.2 Explain the purpose of the oil in which the transformer core and windings are immersed. (2)
- 3.3 State TWO factors that may cause overheating in a transformer. (2)
- 3.4 Name TWO types of transformer losses. (2)
- 3.5 Name TWO types of protective devices used in transformers. (2)
- 3.6 FIGURE 3.1 represents a three-phase transformer.

**FIGURE 3.1: THREE-PHASE TRANSFORMER**

- 3.6.1 Calculate the primary phase voltage. (2)
- 3.6.2 Calculate the secondary phase voltage. (3)
- 3.6.3 Calculate the turns ratio. (3)
- 3.6.4 Explain why the value of the secondary line current is more than the value of the primary line current. (2)

**[20]**

**QUESTION 4: THREE-PHASE MOTORS AND STARTERS**

- 4.1 Name TWO parts of a three-phase induction motor. (2)
- 4.2 State TWO advantages of a three-phase induction motor over a single-phase induction motor. (2)
- 4.3 The nameplate of a three-phase induction motor contains specific information about that motor. List THREE key motor features that would appear on the nameplate. (3)
- 4.4 A three-phase induction motor is connected across a 380 V/60 Hz supply. The motor has a total of 12 poles per phase and a per unit slip of 0,04.

Given:

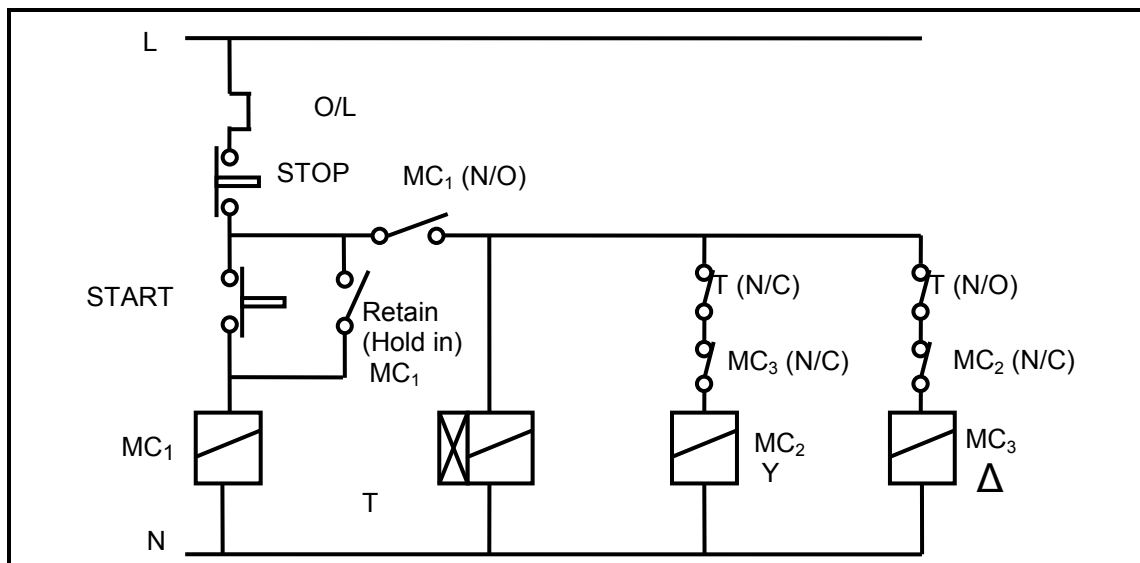
$$\begin{aligned}V_L &= 380 \text{ V} \\f &= 60 \text{ Hz} \\p &= 6 \\ \text{Slip} &= 0,04\end{aligned}$$

Calculate the:

- 4.4.1 Synchronous speed (3)
- 4.4.2 Rotor speed (3)
- 4.5 Explain why it is important to carry out a mechanical inspection on an electrical motor before it is energised. (2)
- 4.6 State TWO electrical inspections that must be carried out on an electrical motor before it is energised. (2)
- 4.7 Explain the function of an overload unit in a motor starter. (3)



4.8 FIGURE 4.1 represents the control circuit of a star-delta starter.



**FIGURE 4.1: CONTROL CIRCUIT OF A STAR-DELTA STARTER**

- 4.8.1 State the function of a star-delta starter. (1)
- 4.8.2 State the mode the motor will be connected in when running at full load. (1)
- 4.8.3 Explain the function of the contacts Retain (Hold in) MC<sub>1</sub>. (3)
- 4.8.4 State, with a reason, what would happen to contact T (N/C) when the timer contactor is energised. (2)
- 4.8.5 Describe the interlocking that prevents the star and delta contactors from being energised at the same time. (6)

4.9 A three-phase delta-connected motor draws a current of 12 A when connected to a 380 V/50 Hz supply. The motor has a power factor of 0,8 and an efficiency of 90%.

Given:

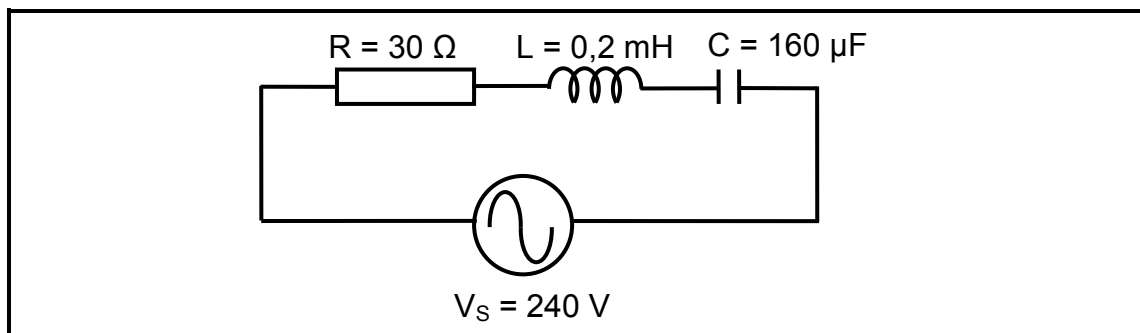
$$\begin{aligned} V_L &= 380 \text{ V} \\ I_L &= 12 \text{ A} \\ f &= 50 \text{ Hz} \\ \cos \phi &= 0,8 \\ \eta &= 90\% \end{aligned}$$

- 4.9.1 Calculate the active power of the motor at full load. (3)
- 4.9.2 Explain what would happen to the active power of the motor if the efficiency of the motor is improved. (1)
- 4.9.3 State the relationship between the line current and the phase current of the motor. (1)
- 4.9.4 Explain what would happen to the current drawn by the motor if the power factor of the motor is improved. (2)

**[40]**

**QUESTION 5: RLC**

- 5.1 Describe ONE practical method of obtaining resonant frequency in a parallel RLC circuit. (3)
- 5.2 Name ONE method that could be used to improve a poor power factor. (1)
- 5.3 A parallel RLC circuit is at resonant frequency. Describe what would happen to the current flow if the frequency is decreased below resonant frequency. (3)
- 5.4 Study the circuit in FIGURE 5.1 below and answer the questions that follow.

**FIGURE 5.1: RLC SERIES CIRCUIT**

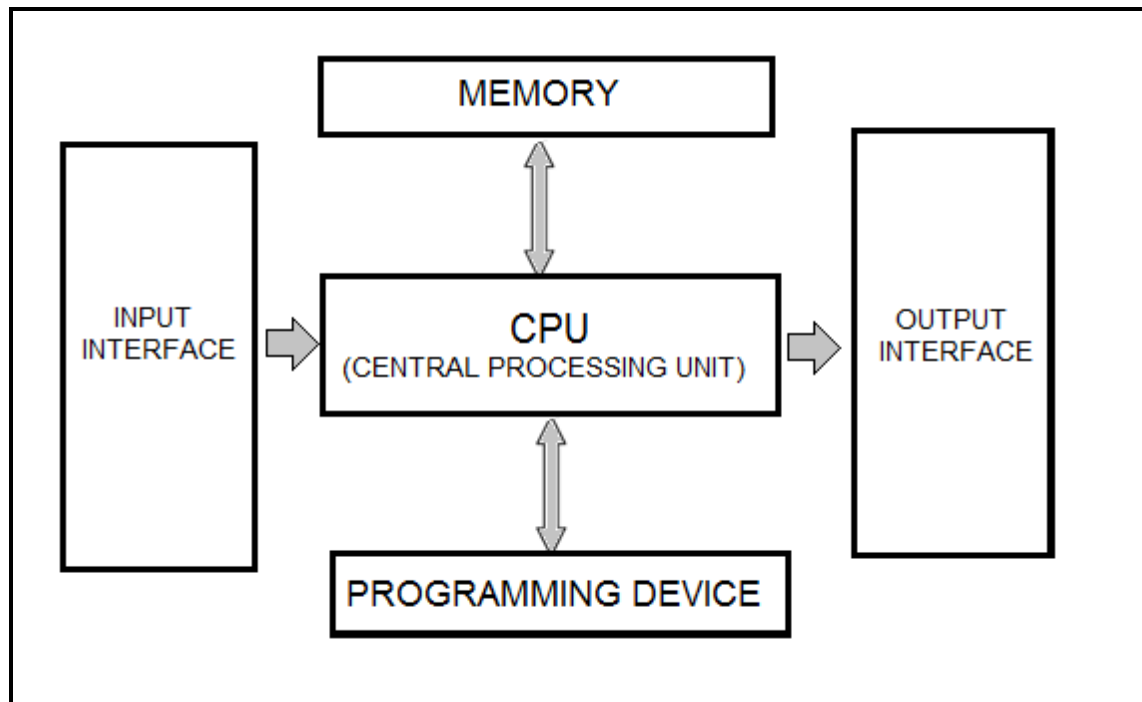
Calculate the:

- 5.4.1 Resonant frequency (3)
- 5.4.2 Total current flowing through the circuit at resonance (3)
- 5.4.3 Q-factor of the circuit (4)
- 5.4.4 The capacitance of the capacitor required for the circuit to be at resonance if the frequency of the supply in FIGURE 5.1 is constant at 1 kHz and the inductance is also constant (3)

**[20]**

**QUESTION 6: LOGIC**

6.1 FIGURE 6.1 represents the block diagram of a PLC system.

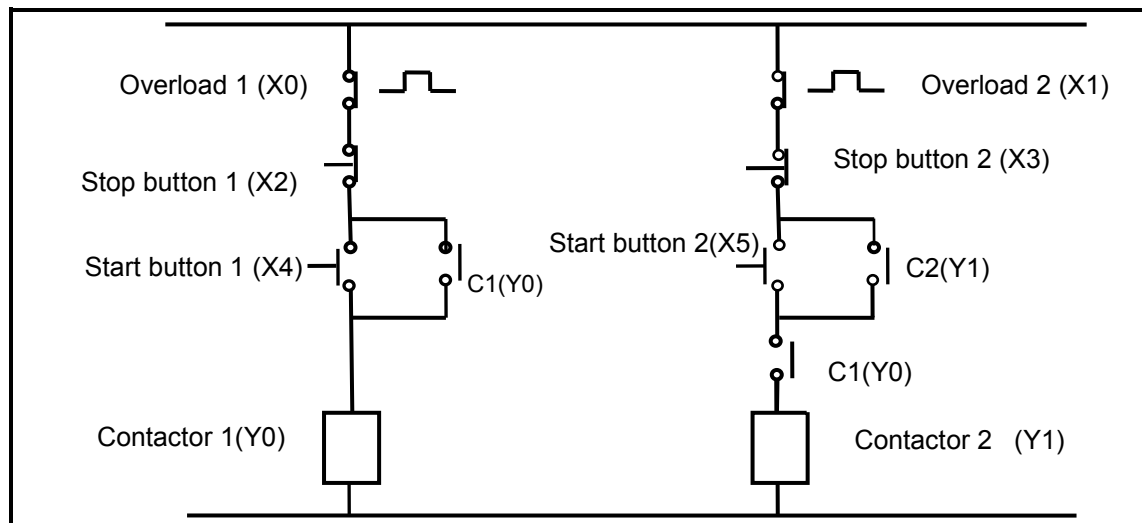


**FIGURE 6.1: PLC SYSTEM**

- 6.1.1 Explain the function of the input interface. (3)
- 6.1.2 Name TWO components that may be connected to the input interface. (2)
- 6.1.3 Name TWO electronic devices, other than a relay, that could be connected to the output interface. (2)
- 6.1.4 Describe the THREE steps that make up the programming scan cycle of a PLC. (6)



6.2 FIGURE 6.2 represents a sequence control diagram.



**FIGURE 6.2: SEQUENCE CONTROL CIRCUIT**

6.2.1 Draw and label the ladder logic diagram of the control circuit using the labels in FIGURE 6.2. (6)

6.2.2 Use a Karnaugh map to simplify the expression below:

$$X = \overline{A} \overline{B} \overline{C} + \overline{A} \overline{B} C + A \overline{B} \overline{C} + A \overline{B} C \quad (6)$$

6.2.3 Using Boolean algebra, simplify the expression below.

$$X = \overline{A} \overline{B} \overline{C} + A \overline{B} \overline{C} + A \overline{B} C + \overline{A} \overline{B} C \quad (7)$$

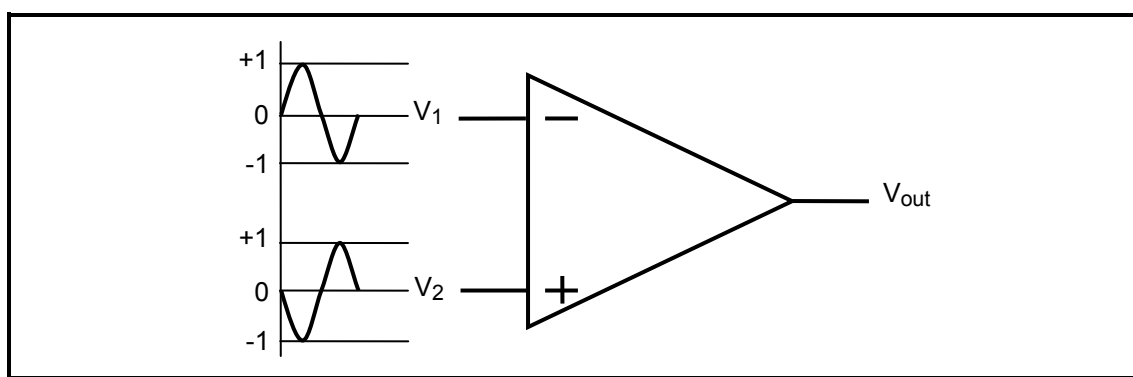
6.2.4 Give ONE example, with an explanation, where a set-reset PLC programming function could be used in industry. (3)

6.2.5 Explain the advantage of using an additional emergency stop switch in a PLC system. (3)

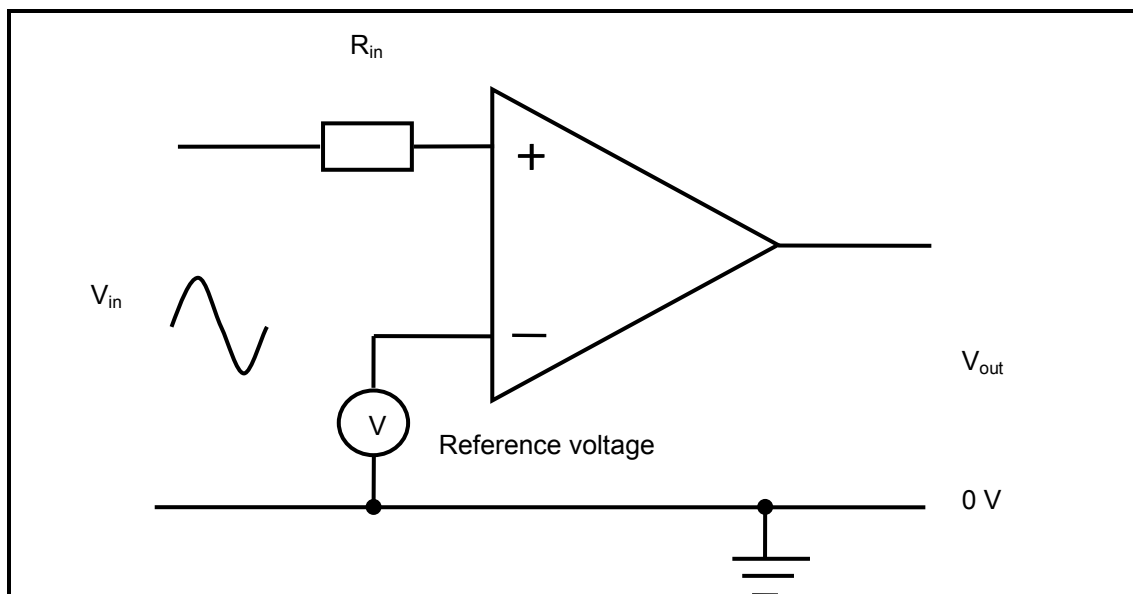
6.3 Explain how an on-delay timer operates. (2)  
**[40]**

**QUESTION 7: AMPLIFIERS**

- 7.1 Define a *basic 741 operational amplifier device*. (3)
- 7.2 Describe the term *infinite bandwidth* with reference to an ideal operational amplifier. (2)
- 7.3 State TWO ideal characteristics of an operational amplifier other than infinite bandwidth. (2)
- 7.4 Describe the following terms with reference to operational amplifiers:
- 7.4.1 Negative feedback (3)
- 7.4.2 Positive feedback (3)
- 7.5 State TWO advantages of negative feedback. (2)
- 7.6 Refer to FIGURE 7.1.

**FIGURE 7.1: OPERATIONAL AMPLIFIER**

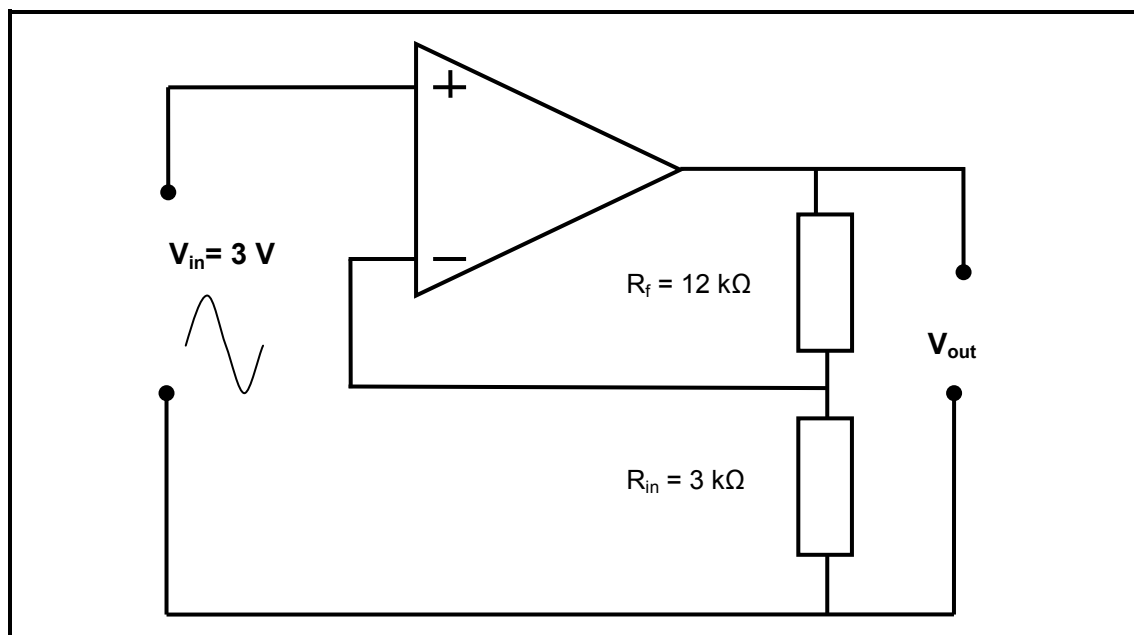
- Redraw the inputs shown and then draw the output of the ideal operational amplifier. (3)
- 7.7 FIGURE 7.2 is a non-inverting voltage comparator.

**FIGURE 7.2: NON-INVERTING VOLTAGE COMPARATOR**

- 7.7.1 Draw the output voltage wave form if the reference voltage is set at 0 V. (3)
- 7.7.2 State ONE application of the operational amplifier. (1)



7.8 FIGURE 7.3 is an operational amplifier circuit.

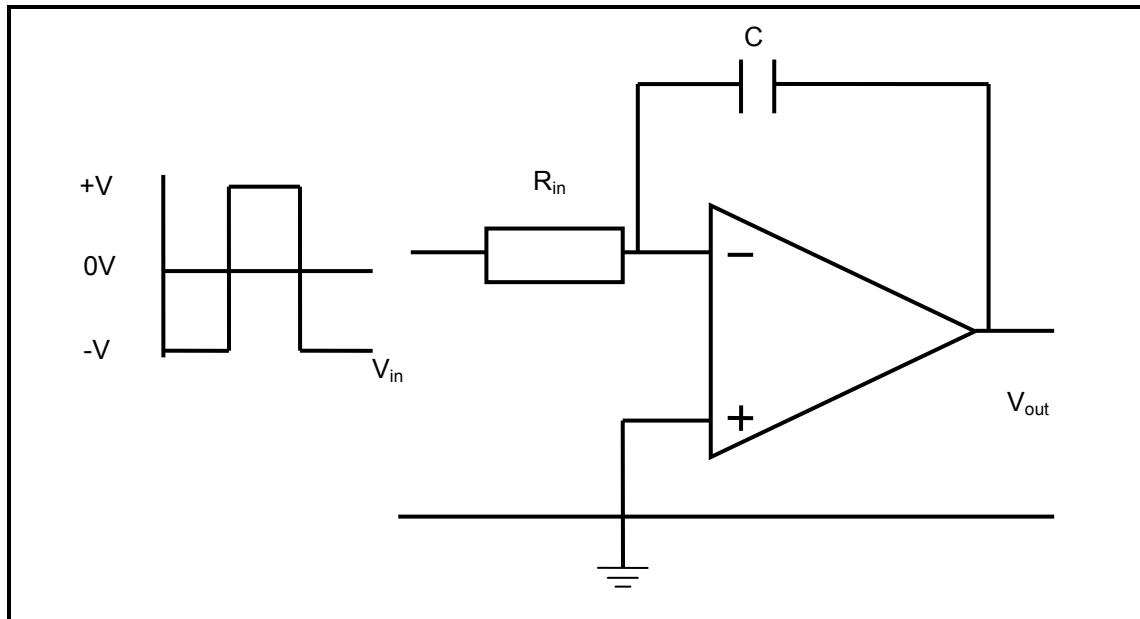


**FIGURE 7.3: OPERATIONAL AMPLIFIER CIRCUIT**

- 7.8.1 Identify the type of operational amplifier circuit in FIGURE 7.3. (1)
- 7.8.2 Redraw the given input signal and then draw the output signal on the same set of axes. (2)
- 7.8.3 Calculate the voltage gain of the amplifier. (3)
- 7.8.4 Calculate the peak output voltage. (3)
- 7.8.5 Explain how the voltage gain of the operational amplifier will change if the value of the resistor  $R_f$  was decreased. (2)
- 7.8.6 Explain the function of  $R_{in}$ . (2)

7.9 Give ONE reason why operational amplifiers are used between stages of complex circuits. (2)

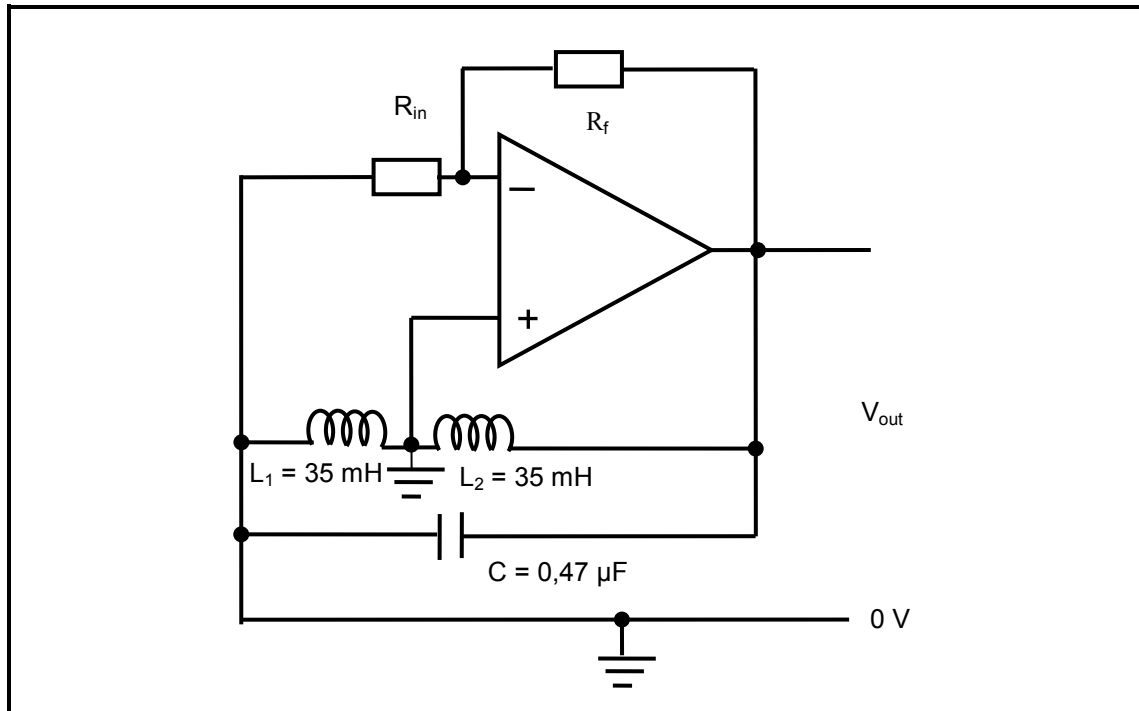
- 7.10 FIGURE 7.4 is an operational amplifier connected in the configuration of an integrator circuit.



**FIGURE 7.4: INTEGRATOR OPERATIONAL AMPLIFIER**

- 7.10.1 Draw the output wave form of the circuit. (3)
- 7.10.2 Describe the specific function that  $R_{in}$  and  $C$  perform. (3)

7.11 FIGURE 7.5 is an operational amplifier connected in an oscillator configuration.



**FIGURE 7.5: OSCILLATOR OPERATIONAL AMPLIFIER**

- 7.11.1 Identify the oscillator configuration in FIGURE 7.5. (1)
- 7.11.2 Calculate the frequency of the oscillator if each coil has an inductance of  $35 \text{ mH}$  and the capacitor has a capacitance of  $0,47 \text{ }\mu\text{F}$ . (6)
- [50]**

**TOTAL: 200**



**FORMULA SHEET****THREE-PHASE AC GENERATION****Star**

$$V_L = \sqrt{3} V_{PH}$$

$$I_L = I_{PH}$$

**Delta**

$$I_L = \sqrt{3} I_{PH}$$

$$V_L = V_{PH}$$

$$P = \sqrt{3} V_L \times I_L \cos \theta$$

$$S = \sqrt{3} V_L I_L$$

$$Q = \sqrt{3} V_L I_L \sin \theta$$

$$\cos \theta = \frac{P}{S}$$

$$Z_{PH} = \frac{V_{PH}}{I_{PH}}$$

**Two wattmeter method**

$$P_T = P_1 + P_2$$

**THREE-PHASE TRANSFORMERS****Star**

$$V_L = \sqrt{3} V_{PH}$$

$$I_L = I_{PH}$$

**Delta**

$$I_L = \sqrt{3} I_{PH}$$

$$V_L = V_{PH}$$

$$P = \sqrt{3} V_L I_L \cos \theta$$

$$S = \sqrt{3} V_L I_L$$

$$Q = \sqrt{3} V_L I_L \sin \theta$$

$$\cos \theta = \frac{P}{S}$$

$$\frac{V_{PH(p)}}{V_{PH(s)}} = \frac{N_P}{N_S} = \frac{I_{PH(s)}}{I_{PH(p)}}$$

**RLC CIRCUITS**

$$X_L = 2\pi fL$$

$$X_C = \frac{1}{2\pi fC}$$

$$f_r = \frac{1}{2\pi\sqrt{LC}}$$

**Series**

$$I_T = I_R = I_C = I_L$$

$$Z = \sqrt{R^2 + (X_L \approx X_C)^2}$$

$$V_L = I X_L$$

$$V_C = I X_C$$

$$V_T = I Z$$

$$V_T = \sqrt{V_R^2 + (V_L \approx V_C)^2}$$

$$I_T = \frac{V_T}{Z}$$

$$\cos \theta = \frac{R}{Z}$$

$$\cos \theta = \frac{V_R}{V_T}$$

$$Q = \frac{X_L}{R}$$

**Parallel**

$$V_T = V_R = V_C = V_L$$

$$I_R = \frac{V_R}{R}$$

$$I_C = \frac{V_C}{X_C}$$

$$I_L = \frac{V_L}{X_L}$$

$$I_T = \sqrt{I_R^2 + (I_L \approx I_C)^2}$$

$$\cos \theta = \frac{I_R}{I_T}$$

$$Q = \frac{X_L}{R}$$



**THREE-PHASE MOTORS AND STARTERS****Star**

$$V_L = \sqrt{3} V_{PH}$$

$$I_L = I_{PH}$$

**Delta**

$$I_L = \sqrt{3} I_{PH}$$

$$V_L = V_{PH}$$

**Power**

$$P = \sqrt{3} V_L I_L \cos \theta$$

$$S = \sqrt{3} V_L I_L$$

$$Q = \sqrt{3} V_L I_L \sin \theta$$

$$\text{Efficiency } (\eta) = \frac{P_{in} - \text{losses}}{P_{in}}$$

**Speed**

$$n_s = \frac{60 \times f}{p}$$

$$\text{Slip}_{\text{Per Unit}} = \frac{n_s - n_r}{n_s}$$

$$n_r = n_s (1 - S_{\text{Per Unit}})$$

$$\% \text{ slip} = \frac{n_s - n_r}{n_s} \times 100\%$$

**OPERATIONAL AMPLIFIERS**

$$\text{Gain } A_v = -\frac{V_{out}}{V_{in}} = -\left(\frac{R_f}{R_{in}}\right) \text{ inverting op amp}$$

$$\text{Gain } A_v = \frac{V_{out}}{V_{in}} = 1 + \frac{R_f}{R_{in}} \text{ non - inverting op amp}$$

$$f_r = \frac{1}{2\pi\sqrt{LC}} \text{ Hartley - oscillator}$$

$$f_{RC} = \frac{1}{2\pi\sqrt{6RC}} \text{ RC - phase - shift oscillator}$$

$$V_{Out} = (V_1 + V_2 + \dots V_N)$$

