



Province of the  
**EASTERN CAPE**  
EDUCATION

**NATIONAL  
SENIOR CERTIFICATE**

**GRADE 12**

**SEPTEMBER 2021**

**MECHANICAL TECHNOLOGY:  
(FITTING AND MACHINING)  
MARKING GUIDELINE**

**MARKS: 200**

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This marking guideline consists of 14 pages.

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**QUESTION 1: MULTIPLE-CHOICE QUESTIONS (GENERIC)**

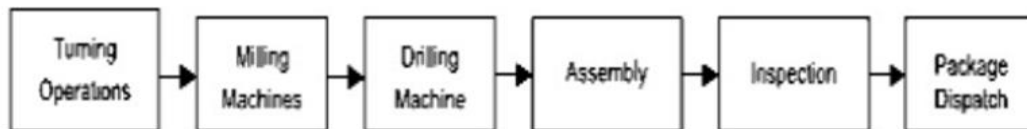
- 1.1 C ✓  
 1.2 D ✓  
 1.3 D ✓  
 1.4 A ✓  
 1.5 B ✓  
 1.6 B ✓

(6 x 1) [6]

**QUESTION 2: SAFETY (GENERIC)****2.1 Safety Precautions**

- Pressure gauges must be checked and tested regularly and adjusted or replaced if any malfunctioning occurs. ✓
- Supporting pins that keep the platform at a desired height on the frame must be inspected for damage. ✓
- Check the floor for oil and apparatus for leaks. ✓
- The platform on which the workpiece rests must be rigid and square with the press cylinder. ✓

(Any 2 x 1) (2)

**2.2 Product layout**

✓✓ (2)

**2.3 Perspex shield**

is installed to shield flying objects from harming the operator's eye. ✓

(1)

**2.4 2.4.1 Machine Identification**

Surface grinder ✓

(1)

**2.4.2 Surface grinder parts label**

- A Workpiece ✓  
 B Machine spindle ✓  
 C Magnetic table ✓  
 D Grinding wheel ✓

(4)

**[10]**

**QUESTION 3: MATERIALS (GENERIC)**

- 3.1 Heat treatment refers to heating and cooling of metals under controlled conditions in their solid state so as to change their properties. ✓✓ (2)

3.2 **Heat treatment properties**

PROCESS		PROPERTY
3.2.1	Hardening	Very hard, high tensile strength and brittle ✓
3.2.2	Tempering	Tough, hard ✓
3.2.3	Annealing	Soft, ductile, low tensile strength ✓
3.2.4	Normalising	Tough and machinable ✓

(4)

3.3 **Purpose of case-hardening**

- It hardens the surface. ✓
- It provides a wear resistant surface. ✓
- Strengthens core to withstand applied loads. ✓ (Any 2 x 1) (2)

3.4 **Carbon effect**

Steel with low carbon content ✓ will not respond very much to the hardening process. ✓ (2)

3.5 **Workshop tests on materials**

Sound test ✓  
 Bend test ✓  
 Filing test  
 Machining test (Any 2 x 1) (2)

3.6 **Reasons for annealing**

- To relieve internal stresses that may have been set up during other processes. ✓
- To soften them in order to facilitate the machining processes. ✓
- To make material ductile.
- Refine their grain structures.
- Reduce brittleness (Any 2 x 1) (2)

**[14]**

**QUESTION 4: MULTIPLE-CHOICE QUESTIONS (SPECIFIC)**

- 4.1 A ✓  
 4.2 D ✓  
 4.3 A ✓  
 4.4 A ✓  
 4.5 A ✓  
 4.6 B ✓  
 4.7 A ✓  
 4.8 C ✓  
 4.9 D ✓  
 4.10 B ✓  
 4.11 B ✓  
 4.12 A ✓  
 4.13 A ✓  
 4.14 B ✓

(14 x 1) [14]

**QUESTION 5: TERMINOLOGY (LATHE AND MILLING MACHINE) (SPECIFIC)****5.1 Lathe Taper turning**

$$5.1.1 \quad \text{Set-over} = \frac{D-d}{2} \times \frac{\text{Length of workpiece}}{\text{length of taper}}$$

$$= (75-50)/2 \times 400 / 250 \quad \checkmark$$

$$= 12.5 \times 1.6$$

$$= 20 \text{ mm} \quad \checkmark$$

(2)

$$5.1.2 \quad \tan \frac{\theta}{2} = \frac{x}{L} \quad \checkmark$$

$$= 12.5 / 250$$

$$= 0.05$$

$$= \tan^{-1} 0.05 \times 2 \quad \checkmark$$

$$\Theta = 5.724^\circ \quad \checkmark$$

(3)

**5.2 Milling Cutters.**

- 5.2.1 A – Helical milling cutter ✓  
 B – Side and face Cutter/ also Accept Staggered tooth cutter ✓  
 C – Dovetail ✓  
 D – T-Slot ✓  
 E – End mill ✓

(5)

**5.3 Cutting Square Threads**

$$5.3.1 \quad \text{Lead} = \text{Pitch} \times \text{Number of Starts}$$

$$= 2 \times 12 = 24 \text{ mm} \quad \checkmark$$

(1)

$$5.3.2 \quad \text{Mean Diameter} = \text{OD} - 0,5 \text{ Pitch}$$

$$= 85 - 0,5 \times 12 \quad \checkmark$$

$$= 91 \text{ mm} \quad \checkmark$$

(2)

$$5.3.3 \quad \tan \theta = \text{Lead} / \pi \times \text{Dm}$$

$$\tan \theta = 24 / 91 \quad \checkmark$$

$$\Theta = 14,77^\circ \quad \checkmark$$

(2)

**5.4 Dividing Head components**

A – Index plate: the aim of the index plate is to enable one revolution of the crank to be further subdivided into fractions of a revolution, especially where the fraction is not a factor of 40. ✓

D – Worm-shaft with a Single – start worm engages with a worm gear with 40 teeth. ✓

E – Worm wheel/gear obtain a rotary movement of the spindle. ✓

(3)  
[18]

**QUESTION 6: TERMINOLOGY (INDEXING) (SPECIFIC)****6.1 GEAR CALCULATIONS:**

6.1.1 Gang Milling: Simultaneously using several cutters of different diameters and forms on the arbor, workpiece can be machined to size in one movement of the milling machine table. ✓ (1)

6.1.2 Straddle Milling: consists of two side and face cutters, separated by spacing collars of required dimensions to produce parallel work in one cut. ✓ (1)

**6.2 Procedure to cut external metric V-screw thread using compound slide method**

- Set up the workpiece in the centre lathe and turn the part to be threaded to the required diameter of the thread. ✓
- Set the compound slide to 30° to the left of the centre line of that cross-slide and set the cutting tool up accurately in the tool post. ✓
- Consult the index plate of the quick-change gear box and shift the levers accordingly for the necessary pitch of the screw thread. ✓
- Start the centre lathe and set the cutting tool at touching point on the workpiece. ✓
- Move the cutting tool a short distance off, to clear the end of the workpiece and feed the compound slide 0.05 mm inwards. ✓
- With the centre lathe revolving, engage the half nuts at the correct line on the threading dial, putting the first cut of the screw thread in progress. ✓
- Stop the centre lathe and check the screw thread pitch with a screw thread pitch gauge. ✓ (Any 5 x 1) (5)

6.3 Definition of Indexing is the process of evenly dividing the circumference of a circular work piece into equally spaced divisions, such as in cutting gear teeth, cutting splines, milling grooves in the reamers and taps. ✓ (1)

**6.4 Milling methods**

- Up-cut milling ✓
- Down-cut milling ✓ (2)

## 6.5 Differential indexing

<i>Hole circles</i>											
<i>Side 1</i>	24	25	28	30	34	37	38	39	41	42	43
<i>Side 2</i>	46	47	49	51	53	54	57	58	59	62	66

<i>Standard change gears</i>										
24 x 2	28	32	40	44	48	56	64	72	86	100

## 6.5.1 Indexing Required

$$\begin{aligned}
 \text{Indexing} &= \frac{40}{A} \quad \checkmark \\
 &= 40/120 \\
 &= \frac{1}{3} \times \frac{22}{22} \quad \checkmark \\
 &= 22/66
 \end{aligned}$$

Indexing is 22 holes in a 66-hole circle ✓

(3)

## 6.5.2 Change of gears

$$\begin{aligned}
 \text{Gear ratio: } \frac{\text{Driver}}{\text{Driven}} &= \frac{A-N}{A} \times \frac{40}{1} \quad \checkmark \\
 &= \frac{120-113}{120} \times 40 \quad \checkmark \\
 &= +\frac{7}{3} \times \frac{8}{8} \quad \checkmark \\
 &= 56/24 \quad \checkmark
 \end{aligned}$$

The driver gear has 56 teeth

The driven gear has 24 teeth ✓

(5)

## 6.5.3 The direction of motion is clockwise

The crank handle will turn the same direction as index plate ✓

(2)

## 6.6 Dove tail Calculations

$$\Theta = 40^\circ$$

$$\alpha = 20^\circ \quad \checkmark$$

$$\begin{aligned}
 x &= r / (\tan \alpha) \\
 &= 10 / (\tan 20) \\
 &= 27,47 \text{ mm} \quad \checkmark
 \end{aligned}$$

$$\begin{aligned}
 X &= 80 + 2R + 2x \quad \checkmark \checkmark \\
 &= 80 + 20 + (2 \times 27,47) \quad \checkmark \\
 &= 154,94 \text{ mm} \quad \checkmark
 \end{aligned}$$

(6)

## 6.7 Types of Milling machines

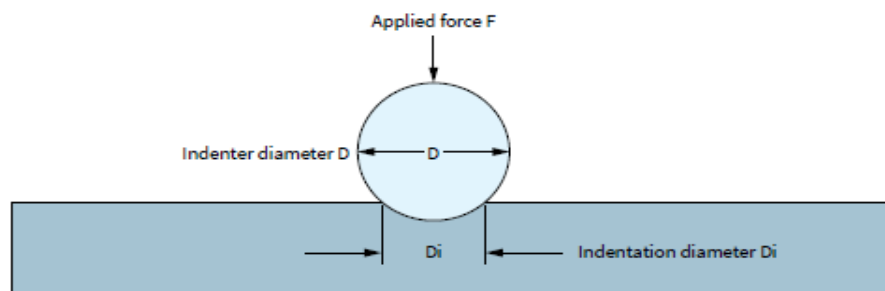
- Vertical milling machine ✓
- Horizontal milling machine ✓

(2)

[28]

**QUESTION 7: TOOLS AND EQUIPMENT (SPECIFIC)****7.1 Hardness Testers****7.1.1 Brinell Hardness tester**

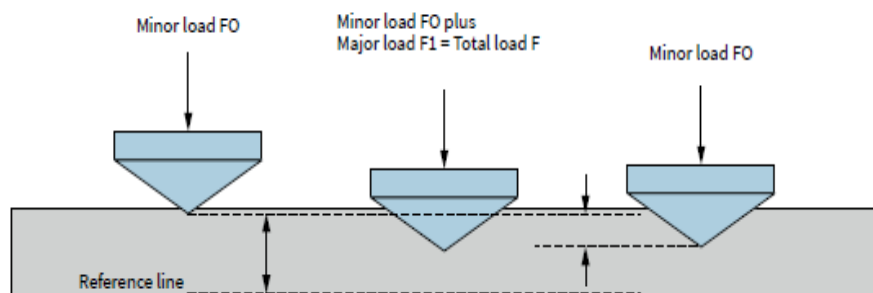
The Brinell Hardness Test involves indenting the test material with a piece hardened steel or carbide ball of 10 mm. The diameter of the indentation left in the test material is measured with a low-powered microscope.



✓✓✓ (3)

**7.1.2 Rockwell Hardness tester**

Rockwell Hardness Test method involves indenting the test material with a diamond cone or hardened steel-ball indenter.

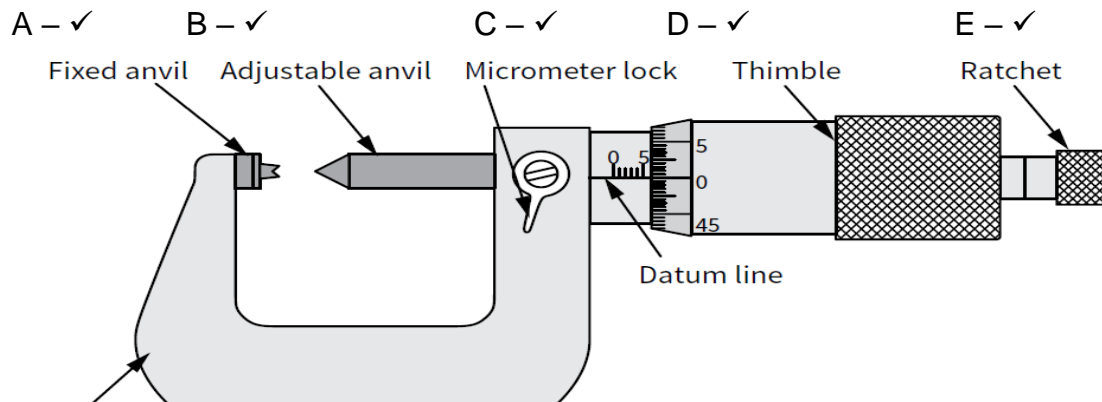


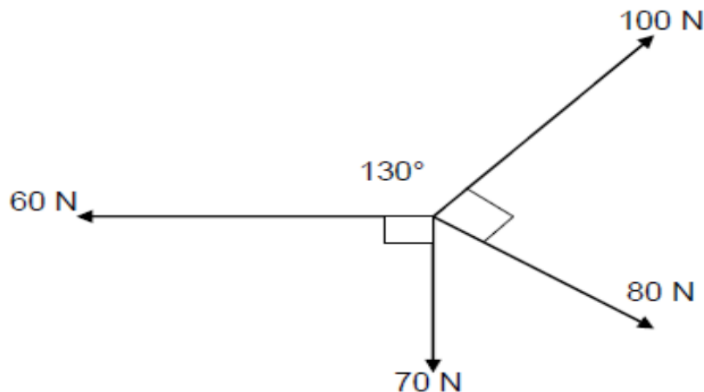
✓✓✓ (3)

**7.2 Hardness measure of a metal.**

- Resistance to penetration ✓
- Elastic hardness ✓
- Resistance to abrasion ✓

(Any 2 x 1) (2)

**7.3 Screw thread micrometre**(5)  
[13]

**QUESTION 8: FORCES (SPECIFIC)****8.1 Resultant Force Calculations:**

$$X_{\text{Com}} = 100 \cos 50 + 80 \cos 40 - 60$$

$$= 65,56 \text{ N}$$

✓

✓

(2)

$$Y_{\text{com}} = 100 \sin 50 - 80 \sin 40 - 70$$

$$= 95,18 \text{ N}$$

✓

✓

(2)

$$R = \sqrt{X^2 + Y^2}$$

$$R = 115.576 \text{ N}$$

✓

$$\tan \theta = y/x$$

✓

$$\tan \theta = 95.18/65.56$$

✓

$$\theta = 55.44$$

$$= 55.44^\circ$$

✓

**Equilibrant = Resultant BUT IN THE OPPOSITE DIRECTION**

$$\text{Equilibrant} = 115.567 \text{ N at } 235.44^\circ$$

✓

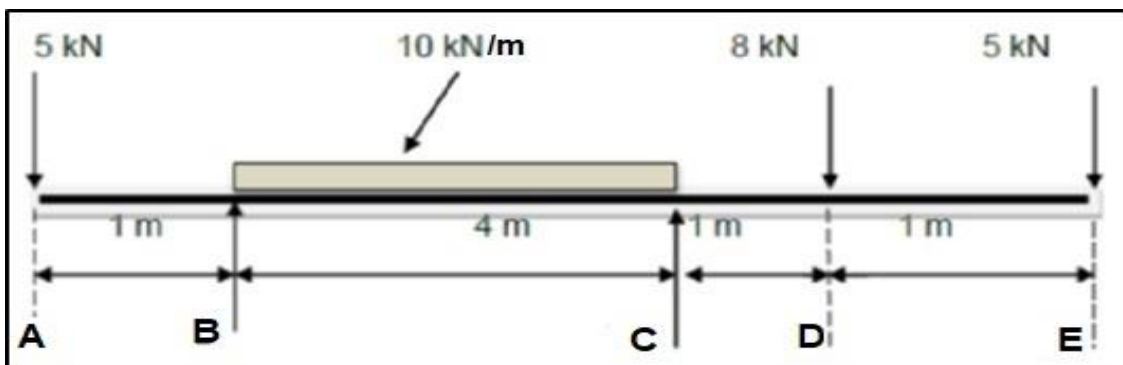
(5)

**8.2 Moments**

Converting the UDL to Point Load

$$4 \times 10 = 40 \text{ kN @ 3 m from the left hand end}$$

✓

**Calculation the Reactions by taking moments:****CLOCKWISE MOMENTS = ANTICLOCK-WISE MOMENTS**

$$(R_C \times 4) + (5 \times 1) = (5 \times 6) + (40 \times 2) + (8 \times 5)$$

✓

$$R_C = 36,25 \text{ kN}$$

✓

$$(R_B \times 4) + (5 \times 2) + (8 \times 1) = (40 \times 2) + (5 \times 5)$$

✓

$$R_B = 21,75 \text{ kN}$$

✓

(5)



### 8.3 Stress Calculations

#### 8.3.1 Tensile Stress Calculations

F = 40 kN; D = 98, d = 67mm: L = 80 mm: E = 90 PGa

$$A = \frac{\pi(D^2 - d^2)}{4} \quad \checkmark$$

$$A = \frac{\pi(0,098^2 - 0,067^2)}{4}$$

$$= 4,02 \times 10^{-3} \text{ m}^2 \quad \checkmark$$

$$\sigma = \frac{F}{A} \quad \checkmark$$

$$\sigma = \frac{40000}{4,02 \times 10^{-3}} \quad \checkmark$$

$$\sigma = 9950248,76 \text{ Pa}$$

$$\sigma = 9,95 \text{ MPa} \quad \checkmark$$

(5)

#### 8.3.2 The Strain calculations

$$\varepsilon = \frac{\sigma}{E} \quad \checkmark$$

$$\varepsilon = \frac{9,95 \times 10^6}{90 \times 10^9} \quad \checkmark$$

$$= 0,11 \times 10^{-3}$$

$$\text{or } 1,11 \times 10^{-4} \quad \checkmark$$

(3)

#### 8.3.3 Change in length

$$\varepsilon = \frac{\Delta l}{l} \quad \checkmark$$

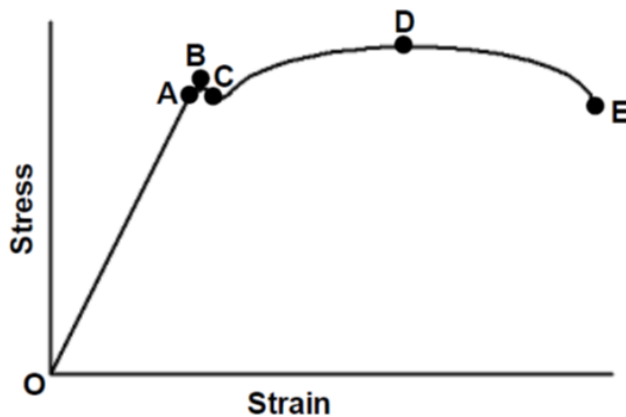
$$\Delta l = \varepsilon \times l \quad \checkmark$$

$$= (0,11 \times 10^{-3}) \times 0,08$$

$$= 8,8 \times 10^{-6} \text{ m} \quad \checkmark$$

$$= 8,8 \times 10^{-3} \text{ mm} \quad (3)$$

#### 8.4 Stress/Strain diagram



✓ (Diagram shape)

- |                              |   |
|------------------------------|---|
| A – Limit of Proportionality | ✓ |
| B – Elastic limit            | ✓ |
| C – Yield point              | ✓ |
| D – Maximum Force/Point      | ✓ |
| E – Point of Fracture        | ✓ |

(6)

8.5 FOS stands for Factor Of Safety or Safety Factor. ✓✓

(2)

[33]

### QUESTION 9: MAINTENANCE

#### 9.1 Material Classifications

- |       |  |     |
|-------|--|-----|
| 9.1.1 | PVC – Thermoplastic ✓                  | (1) |
| 9.1.2 | Glass fibre – Thermo-setting plastic ✓ | (1) |
| 9.1.3 | Nylon – Thermoplastic ✓                | (1) |

#### 9.2 Reasons for using cutting fluid when working on the centre lathe.

- It prolongs the life of a cutting tool. ✓
- It prevents the shavings or metal chips from sticking and fusing to the cutting tool. ✓
- It will carry away the heat generated by the turning process.
- It flushes away shavings/metal chips.
- It improves the quality of the finish of the turned surface. (Any 2 x 1) (2)

#### 9.3 Gear Drives Maintenance.

- Checking and replenishment of lubrication levels ✓
- Ensuring that gears are properly secured to shafts ✓
- Cleaning and replacement of oil filters
- Reporting excessive noise and wear, vibrations and overheating for expert attention. (Any 2 x 1) (2)

## 9.4 Reasons for the use of carbon fibre

- It is light in weight. ✓
- It is tougher and stronger. ✓
- It can be bent to any shape when heated above 150 °C. (Any 2 x 1) (2)

## 9.5 ONE property and ONE use of each composite

Composite		Property	Uses
9.5.1	Teflon	<ul style="list-style-type: none"> <li>• Resistant to water, grease, heat and corrosion ✓</li> <li>• Needs no lubrication</li> <li>• Very low co-efficient of friction (Any 1)</li> </ul>	Orthopaedic and prosthetic appliances, hearing aids, joints, upholstery, electric insulation and non-stick coating pans ✓ (Any 1)
9.5.2	Vesconite	<ul style="list-style-type: none"> <li>• Withstands high temperatures</li> <li>• self lubrication ✓</li> <li>• resistant to water, grease heat and corrosion.</li> <li>• good machinability. (Any 1)</li> </ul>	<ul style="list-style-type: none"> <li>• Orthopaedic and prosthetic appliances. ✓</li> <li>• Hearing aid</li> <li>• Upholstery (Any 1)</li> </ul>
9.5.3	Baskelite	<ul style="list-style-type: none"> <li>• heat resistant ✓</li> <li>• Brittle in nature (Any1)</li> </ul>	<ul style="list-style-type: none"> <li>• Aircraft Components, bearings, brake linings and laminated material ✓ (Any1)</li> </ul>

(6)

- 9.6
- Contact pressure ✓
  - Temperature ✓
  - Sliding velocity ✓
  - Type of a lubricant ✓
  - Surface roughness ✓

(Any 3 x 1) (3)

**[18]**

**QUESTION 10: JOINING METHODS (SPECIFIC)****10.1 Square Thread Calculations:**

$$T = 48 \text{ mm} ; m = 3$$

$$10.1.1 \quad \text{PCD} = T \times m \\ = 48 \times 3 = \mathbf{144 \text{ mm}} \checkmark\checkmark \quad (2)$$

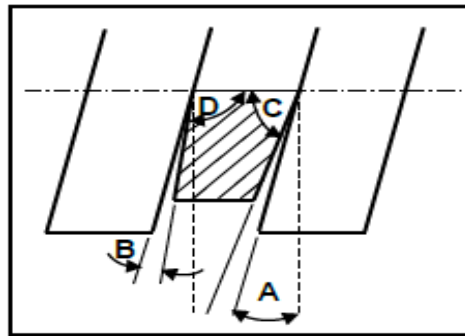
$$10.1.2 \quad \text{Add} = \text{Module} = \mathbf{3 \text{ mm}} \checkmark \quad (1)$$

$$10.1.3 \quad \text{Clearance} = 0,157 \times 3 \\ = \mathbf{0,471 \text{ mm}} \checkmark\checkmark \quad (2)$$

$$10.1.4 \quad \text{Ded} = 1,157 \times 3 \\ = \mathbf{3,471 \text{ mm}} \checkmark\checkmark \quad (2)$$

$$10.1.5 \quad \text{OD} = \text{PCD} + 2 \times 3 \\ = \mathbf{150 \text{ mm}} \checkmark\checkmark \quad (2)$$

$$10.1.6 \quad \text{Circular Pitch} \\ = \pi \times m \\ = \pi \times 3 = \mathbf{9,424 \text{ mm}} \checkmark \quad (1)$$

**10.2 Left-hand square screw thread**

- |                                 |   |     |
|---------------------------------|---|-----|
| A – Leading Angle               | ✓ | (1) |
| B – Following or Trailing Angle | ✓ | (1) |
| C – Clearance                   | ✓ | (1) |
| D – Helix angle                 | ✓ | (1) |

10.3 A multi-start thread allows for a faster travel or movement and is more efficient as it loses less power through friction compared to single start thread. ✓✓ (2)

10.4 Screw Thread fit is a combination of allowances and tolerances and a measure of tightness or looseness between the bolt and nut. ✓✓ (2)

**[18]**

**QUESTION 11: SYSTEMS AND CONTROL (DRIVE SYSTEMS) (SPECIFIC)**

11.1 Rotational velocity is where a body rotates (spin) around its axis. It is the rotation rate or how fast a body revolves or turns. It is measured in radians per second. ✓✓ (2)

**11.2 Hydraulic system calculations****11.2.1 Calculate the Fluid pressure**

$$\begin{aligned}
 A_A &= \frac{\pi D_A^2}{4} && \checkmark \\
 &= \frac{\pi 0.04^2}{4} && \checkmark \\
 &= 1,26 \times 10^{-3} \text{ m}^2
 \end{aligned}$$

$$\begin{aligned}
 P_A &= \frac{F_A}{A_A} && \checkmark \\
 &= \frac{275}{1,2566 \times 10^{-3}} \text{ Pa} && \checkmark \\
 &= 218844 \text{ Pa} && \checkmark \\
 &= 218,84 \text{ kPa} && (4)
 \end{aligned}$$

**11.2.2 Load on the piston B**

$$\begin{aligned}
 A_B &= \frac{\pi D^2}{4} \\
 &= \frac{\pi 0.075^2}{4} \\
 &= 4,42 \times 10^{-3} \text{ m}^2 && \checkmark
 \end{aligned}$$

$$\begin{aligned}
 P_B &= \frac{F_B}{A_B} && \checkmark \\
 F_B &= P_B \times A_B && \checkmark \\
 &= (218,85 \times 10^3) \times (4,42 \times 10^{-3}) && \checkmark \\
 &= 967,32 \text{ N} \\
 \text{Mass} &= \frac{967,32 \text{ N}}{10} && \checkmark \\
 &= 96,73 \text{ kg} && (4)
 \end{aligned}$$

**11.2.3 Hydraulic System Applications**

- Machine tools, ✓ motor vehicle, ✓ hydraulic jacks ✓ (Any 2 x 1) (2)

11.3 Hydraulics refers to the transmission and control of forces and movement by means of fluid. Fluid (generally oil) is used to transmit energy. ✓✓ (2)

### 11.4 Belt Drive Calculations


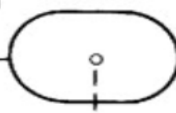
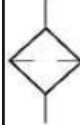
$$N_{\text{motor}} \times D_{\text{motor}} = N_{\text{blade}} \times D_{\text{blade}}$$

$$130 \times 1205 = 385 \times D_{\text{blade}} \quad \checkmark$$

$$D_{\text{blade}} = 406,883 \text{ pm} \quad \checkmark$$

(2)

### 11.5 Pneumatic symbols

11.5.1	Pump	 Pump ✓✓
11.5.2	Air receiver	 Receiver ✓✓
11.5.3	Filter	 Filter ✓✓

(6)

### 11.6 Gear-Drive system calculations:

Data:

#### 11.6.1 Rotation speed of Electric motor

$$\frac{N_{\text{INPUT}}}{N_{\text{OUTPUT}}} = \frac{T_B \times T_D \times T_F}{T_A \times T_C \times T_E}$$

$$N_{\text{INPUT}} = \frac{T_B \times T_D \times T_F}{T_A \times T_C \times T_E} \times N_{\text{OUTPUT}} \quad \checkmark$$

$$N_{\text{INPUT}} = \frac{36 \times 46 \times 60}{18 \times 16 \times 40} \times 160 \quad \checkmark$$

$$= 1380 \text{ r/min} \quad \checkmark$$

(3)

#### 11.6.2 Velocity ratio

$$VR = \frac{N_{\text{INPUT}}}{N_{\text{OUTPUT}}}$$

$$= \frac{1380}{160} \quad \checkmark$$

$$= 8,625:1$$

$$= 8,63:1 \quad \checkmark$$

(2)

#### 11.6.3 Driven will rotate Clockwise ✓

(1)

[28]

TOTAL: 200